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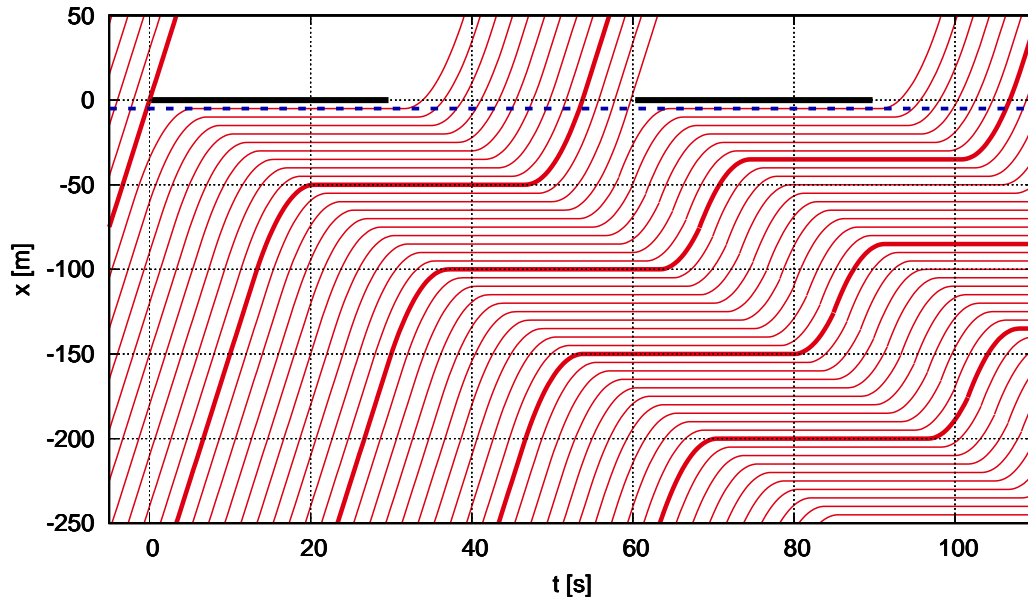
Exam to the Lecture
Traffic Dynamics and Simulation
SS 2022

Total 120 points

Problem 1 (20 points)

- (a) In microscopic models, the main dynamical elements are the vehicles and drivers (driver-vehicle unit) while, in macroscopic models, this is aggregated to locally averaged, mostly continuous spatiotemporal quantities.
- Variables micro: speed v_i , gap to the leader s_i , acceleration \dot{v}_i of vehicle i
 - Macro: Local density $\rho(x, t)$, speed $V(x, t)$, flow $Q(x, t)$
- (b) Which class is better suited?
- (i) Generating the surrounding traffic in driving simulators: Only micro because you need individual vehicles.
 - (ii) Traffic state estimation and short-term prediction: Macro, because you do not have the complete microscopic information to drive microscopic models.
 - (iii) Determining the effects of speed limits on the traffic flow: As in all situations concerning heterogeneous traffic (here, trucks and cars), microscopic models are better. (Though macromodels not principally impossible).
 - (iv) Real-time traffic-dependent navigation: Macro, because only the macroscopic quantities “travel times” are needed and microscopic information to drive micromodels generally is not given.
 - (v) Determining the effects of assisted or autonomous vehicles on the surrounding traffic flow: Micro, because the response to individual surrounding vehicles is needed.

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Problem 2 (40 points)

(a) Maximum density during queuing phases:

$$\rho_{\max} = \frac{10 \text{ veh}}{50 \text{ m}} = 200 \text{ veh/km}$$

Outflow Q_{out} at $x = 50 \text{ m}$ during the interval $[40 \text{ s}, 60 \text{ s}]$:

$$Q_{\text{out}} = \frac{10 \text{ veh}}{20 \text{ s}} = 0.5 \text{ veh/s} = 1800 \text{ veh/h}$$

- (b) – Density: $\rho_{\text{in}} = 7 \text{ veh}/200 \text{ m} = 35 \text{ veh/km}$ (anything between 30 veh/km and 35 veh/km is OK; true density 33.3 veh/km)
 – Flow: $Q_{\text{in}} = 10 \text{ veh}/20 \text{ s} = 0.5 \text{ veh/s} = 1800 \text{ veh/h}$
 – Speed: $V_{\text{in}} = Q_{\text{in}}/\rho_{\text{in}} = 52 \text{ km/h}$ (anything between 50 km/h and 55 km/h is OK; true speed 15 m/s=54 km/h)

(c) Between 30 s and 90 s, there is oversaturated traffic, so the cycle-averaged capacity is given by

$$C_{\text{TL}} = \frac{13 \text{ veh}}{60 \text{ s}} = 0.216 \text{ veh/s} = 780 \text{ veh/h}$$

Since the inflow $Q_{\text{in}} = 1800 \text{ veh/h}$, this is clearly not sufficient.

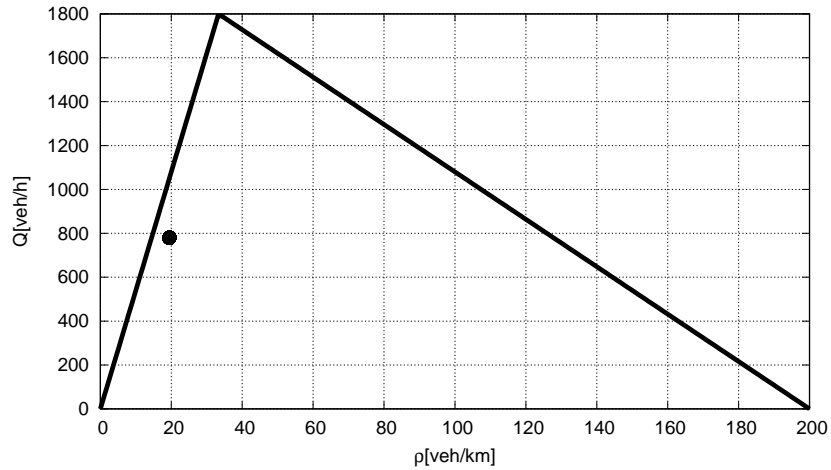
(d) Wave velocity from the transition congested-free, e.g., starting at $t = 30 \text{ s}$ and $x = 0$:

$$w = \frac{-200 \text{ m}}{96 \text{ s} - 30 \text{ s}} = -3 \text{ m/s}$$

- (e) The fundamental diagram (FD) is determined by the already determined quantities V_0 , Q_{\max} , and w :

$$Q(\rho) = \min(V_0\rho, w(\rho - \rho_{\max}))$$

or, intuitively, just a triangle with the corners $(0, 0)$, $(\rho_{\max}, 0)$, and the free-flow and congested gradients v_0 and w , respectively



- (f) We have $n = 13$ data points and an average speed (watch out - transform the speeds in m/s) of $V_{\text{data}} = \sum_i v_i/n = 11.1$ m/s, so

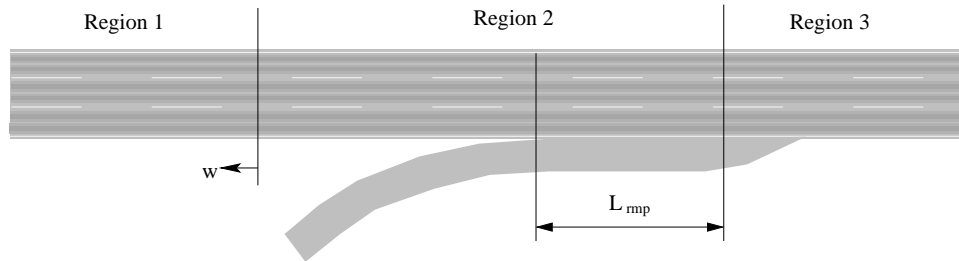
$$Q_{\text{data}} = 13/60 \text{ veh/s} = 780 \text{ veh/h}, \quad \rho_{\text{data}} = Q_{\text{data}}/V_{\text{data}} = 0.0194 \text{ veh/m} = 19.4 \text{ veh/km}$$

Because this data point contains a mix of stopped and outflowing traffic, it does not lay on a homogeneous steady state, hence, not on the FD

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Problem 3 (40 points)

Given is a three-lane freeway section with an onramp:



Traffic flow is described by a LWR model with the tridiagonal fundamental diagram

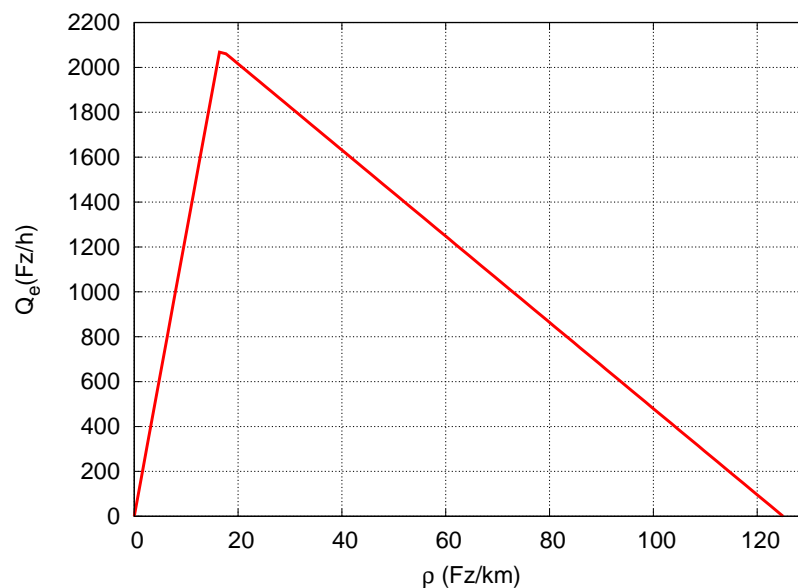
$$Q_e(\rho) = \min \left[V_0 \rho, \frac{1}{T} (1 - l_{\text{eff}} \rho) \right].$$

- (a) Ramp term of the continuity equations for the effective densities and flows for 3 lanes:

$$\frac{\partial \rho}{\partial t} + \frac{\partial Q}{\partial x} = \eta_{\text{rmp}}, \quad \eta_{\text{rmp}} = \frac{Q_{\text{rmp}}}{3 * 0.3 \text{ km}} = 1333 \text{ veh/h/km}$$

- (b) The corners of the triangular FD are $(0, 0)$, $(\rho_{\text{max}}, 0)$, and (ρ_c, Q_{max}) where, for normal weather, we have

$$\rho_{\text{max}} = \frac{1}{l_{\text{eff}}} = 125 \text{ veh/km}, \quad \rho_c = \frac{1}{v_0 T + l_{\text{eff}}} = 16.5 \text{ veh/km}, \quad Q_{\text{max}} = V_0 \rho_c = 2083 \text{ veh/h}$$



- (c) The total demand of the main road and the ramp flow realized in region 3 if there is no breakdown is given by the sum of the inflow Q_1^{tot} and the on-ramp flow,

$$Q_3^{\text{tot}} = Q_1^{\text{tot}} + Q_{\text{rmp}} = 4\,800 \text{ veh/h}$$

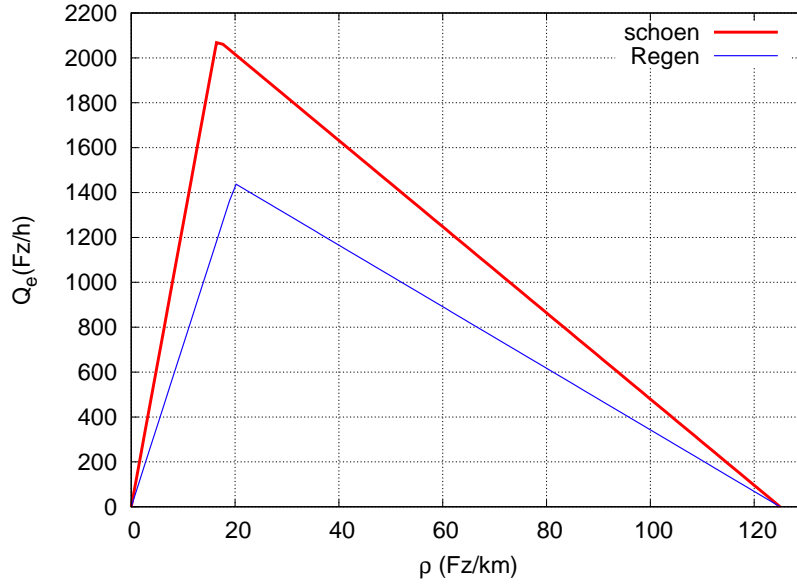
while the capacity of any main-road section is given by

$$C = 3Q_{\text{max}} = 6\,249 \text{ veh/h}$$

This is sufficient, hence no breakdown.

- (d) Behavioural change during a strong thunderstorm: $v_0 = 72 \text{ km/h}$, $T = 2.1 \text{ s}$, $l_{\text{eff}} = 8 \text{ m}$, so

$$\rho_{\text{max}} = \frac{1}{l_{\text{eff}}} = 125 \text{ veh/km}, \quad \rho_c = \frac{1}{v_0 T + l_{\text{eff}}} = 20 \text{ veh/km}, \quad Q_{\text{max}} = V_0 \rho_c = 1\,440 \text{ veh/h}$$



- (e) During the thunderstorm, the main-road capacity is given by $C = 3 * 1\,440 \text{ veh/h} = 4\,320 \text{ veh/h}$ which is greater than the demand $Q_1^{\text{tot}} = 3\,600 \text{ veh/h}$ but less than the traffic $Q_3^{\text{tot}} = 4\,800 \text{ veh/h}$ which the downstream segment must take if there is no breakdown. hence, there is a breakdown soemwhere along the onramp merge section. The resulting lane-average density in the congested region is given by (watch out that congested branches are always calculated for the effective quantities in SI units; anything else is too error prone!)

$$Q_2 = Q_{\text{max}} - \frac{1}{3}Q_{\text{rmp}} = 0.289 \text{ veh/s}, \quad \rho_2 = \rho_{\text{cong}}(Q_2) = \rho_{\text{max}}(1 - Q_2 T) = 0.0491 \text{ veh/m}$$

We also have

$$Q_1 = \frac{Q_{\text{in}}}{3} = 0.333 \text{ veh/s}, \quad \rho_1 = \rho_{\text{free}}(Q_1) = \frac{Q_1}{v_0} = 0.0167 \text{ veh/m}$$

resulting in a propagation velocity of the upstream front of the jam

$$c_{12} = \frac{Q_2 - Q_1}{\rho_2 - \rho_1} = -1.37 \text{ m/s}$$

Problem 4 (20 points)

Consider the decision situation where the driver of a stopped vehicle wants to enter a priority road at an unsignalized intersection.

- (a) The safety criterion is satisfied if the nearest follower f on the main road has to brake at a smaller deceleration than b_{safe} in the case of a positive (enter) decision,

$$\dot{v}_f(s_f, v_f, v_l = 0) > -b_{\text{safe}}.$$

The incentive criterion is always satisfied because, without incentive, the entering driver would wait forever.

- (b) Minimum gap to an arriving upstream vehicle at speed v assuming $a = b = b_{\text{safe}} = 2\text{ m}$: Here, the arriving vehicle is the subject vehicle and the entering vehicle the leading vehicle at speed $v_l = 0$. The IDM+ only decelerates if $v > v_0$ (excluded) or if the interaction regime is active. Hence, the safety criterion (with respect to the approaching vehicle) reads

$$\dot{v} = -a \left(\frac{s^*}{s} \right)^2 = -a \left(\frac{s_0 + vT + v^2/(2\sqrt{ab})}{s} \right)^2 \stackrel{!}{=} -b_{\text{safe}}$$

With $a = b = b_{\text{safe}}$, this simplifies to

$$-b \left(\frac{s_0 + vT + v^2/(2b)}{s} \right)^2 \stackrel{!}{=} -b$$

or

$$s = s_0 + vT + \frac{v^2}{2b}$$

$s - s_0$ is the stopping distance consisting of the reaction distance vT and the braking distance $v^2/(2b)$ provided that the reaction time is assumed to be equal to the desired time gap